## NUMERICAL COMPUTING

Summer 2023

Assignment 4, due before class, Monday June 26, 2023.

Haowen He heh4@rpi.edu

1. Text exercises 2(a), 2(b), and 4 on page 97. Hint: it may be helpful to recall the following formulas valid for  $2 \times 2$  matrices

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \qquad A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} a & b \\ c & d \end{bmatrix}.$$

$$(2a) \qquad A = \begin{pmatrix} 1 & a \\ 3 & 4 \end{pmatrix} \qquad ||A||_{\infty} = \max\{3, 7\} = 7$$
$$A^{-1} = \begin{pmatrix} -2 & 1 \\ \frac{3}{4} & -\frac{1}{4} \end{pmatrix} \qquad ||A^{-1}||_{\infty} = \max\{3, 2\} = 3$$
$$\implies \kappa_{\infty}(A) = 7 \times 3 = |2|_{1}$$

$$(\lambda b) \qquad A = \begin{pmatrix} 1 & \lambda \cdot \circ I \\ 3 & 6 \end{pmatrix} \qquad \|A\|_{\infty} = \max\{3.\circ|, 9\} = 9$$
$$A^{-1} = \begin{pmatrix} -\lambda \circ \circ & 67 \\ 1 \circ \circ & -1^{\infty}/3 \end{pmatrix} \qquad \|A^{-1}\|_{\infty} = \max\{\lambda 67, \frac{4^{00}/3}{3}\} = \lambda 67$$
$$\implies \kappa_{\infty}(A) = 9 \times \lambda 67 = \left\lfloor \frac{1}{24 \circ 3} \right\rfloor_{1/2}$$

$$(4a)\begin{pmatrix} 1 & a & | & 1 \\ a & 4, 01 & a \end{pmatrix} \xrightarrow{R_{a} \rightarrow R_{a} - aR_{1}} \begin{pmatrix} 1 & a & | & 1 \\ 0 & 0.0| & 0 \end{pmatrix} \Rightarrow \begin{cases} 0.0 | X_{a} = 0 \Rightarrow X_{a} = 0 \\ X_{1} + aX_{a} = 1 \Rightarrow X_{1} = 1 \end{cases}$$

$$Actual solution: \quad X = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\Rightarrow X_{c} = (-1, 1)$$

$$Forward error: \quad ||X - X_{c}||_{\infty} = \max\{a, 1\} = a$$

$$Backward error: \quad ||b - Ax_{c}||_{\infty} = \max\{0, 0.0|\} = 0.0|$$

$$Error magnification \quad factor = \frac{reh. forward err}{reh. backward err}$$

$$= \frac{a/1}{0.0|A}$$

$$= \frac{400}{10}$$

(4b)  $\implies x_c = (3, -1)$ Forward error :  $||x - x_c||_{\infty} = \max\{1 - 21, 1\} = 2$ Backward error :  $||b - Ax_c||_{\infty} = \max\{0, 0.01\} = 0.01$ 

> Error magnification factor = reh. forward err reh. backward err

$$= \frac{\frac{\lambda}{1}}{0.01/\lambda}$$

 $(4c) \implies \chi_{c} = (\lambda, -1/\lambda)$ Forward error:  $||\chi - \chi_{c}||_{\infty} = \max \{1-11, 1/\lambda\} = 1$ Backward error:  $||b - A\chi_{c}||_{\infty} = \max \{0, 0.005\} = 0.005$ Error magnification factor  $= \frac{\text{reh. Sorward err}}{\text{reh. backward err}}$   $= \frac{1/1}{0.005/\lambda}$  $= \frac{400}{100}$  2. Computer problem 1 on page 98. For this problem, use  $A_{ij} = 3/(i+2j-1)$  instead of the formula for  $A_{ij}$  given in the text. Be sure to include a brief comment on the result of the comparison. Is the result expected and why.

```
function [] = p2(n)
                A=zeros(n);
                x=ones(n,1);
                for i=1:n
                    for j=1:n
                       A(i,j)=3/(i+2*j-1);
                    end
                end
                b=A*x;
                xc=A\b;
                fe=norm(x-xc, "inf");
rfe=fe/norm(x, "inf");
                be=norm(b-A*xc, "inf");
                rbe=be/norm(b, "inf");
                emf=rfe/rbe;
                condnum=cond(A, inf);
                disp(["forward error: ", num2str(fe)])
                disp(["relative forward error: ", num2str(rfe)])
                disp(["backward error: ", num2str(be)])
                disp(["relative backward error: ", num2str(rbe)])
                disp(["Error Magnification factor: ", num2str(emf)])
                disp(["Condition number of A: ", num2str(condnum)])
           p2(6)
           p2(10)
                "forward error: " "1.8479e-09"
                "relative forward error: " "1.8479e-09"
                "backward error: " "2.2204e-16"
n = 6
                "relative backward error: " "6.042e-17"
                "Error Magnification factor: "
                                                    "30584566.425"
                "Condition number of A: "
                                              "70342013.954"
                "forward error: " "0.0028717"
                "relative forward error: " "0.0028717"
                "backward error: " "4.4409e-16"
\Lambda = |0|
                "relative backward error: " "1.0108e-16"
                "Error Magnification factor: " "28410438423259.55"
                "Condition number of A: "
                                              "131321934554336.8"
```

3. Text exercises 2(a), and 4(b) on page 106. These problems are to be done using hand calculations.

$$(\lambda A) \qquad A = \begin{pmatrix} 1 & 1 & 0 \\ \lambda & 1 & -1 \\ -1 & 1 & -1 \end{pmatrix} \Rightarrow \begin{matrix} Row \ \lambda & has the \\ largest pivot value \\ pivot value \\ \Rightarrow \end{matrix} \stackrel{P}{}^{2} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$
$$PA = \begin{pmatrix} \lambda & 1 & -1 \\ -1 & 1 & -1 \\ 1 & 1 & 0 \\ \end{pmatrix} \frac{R_{\lambda} \Rightarrow R_{\lambda} + \frac{1}{\lambda}R_{1}}{R_{3} \Rightarrow R_{3} - \frac{1}{\lambda}R_{1}} \begin{pmatrix} \lambda & 1 & -1 \\ 0 & \frac{3}{\lambda} & -\frac{3}{\lambda} \\ 0 & \frac{3}{\lambda} & \frac{3}{\lambda} \end{pmatrix} \frac{R_{3} \Rightarrow R_{3} - \frac{1}{3}R_{\lambda}}{R_{3} \Rightarrow R_{3} - \frac{1}{3}R_{1}} \\\begin{pmatrix} \lambda & 1 & -1 \\ 0 & \frac{3}{\lambda} & -\frac{3}{\lambda} \\ 0 & 0 & 1 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \\ \end{pmatrix} = \bigcup \qquad \Rightarrow \qquad \lambda = \begin{pmatrix} 1 & 0 & 0 \\ -\frac{3}{\lambda} & 1 & 0 \\ \frac{3}{\lambda} & \frac{1}{\lambda} \\ 1 & 0 \\ \frac{3}{\lambda} & \frac{3}{\lambda} \\ \frac{3}{\lambda} \\ \frac{3}{\lambda} \\ \frac{3}{\lambda} & \frac{3}{\lambda} \\ \frac{3}{$$

$$(4b) \quad A = \begin{pmatrix} -1 & 0 & 1 \\ a & 1 & 1 \\ -1 & a & 0 \end{pmatrix} \Rightarrow Row \ a has the largest pivot value \Rightarrow P = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

$$PA = \begin{pmatrix} a & 1 & 1 \\ -1 & a & 0 \\ -1 & 0 & 1 \end{pmatrix} \frac{R_a \Rightarrow R_a + \frac{1}{a}R_1}{R_3 \Rightarrow R_3 + \frac{1}{a}R_1} \begin{pmatrix} a & 1 & 1 \\ 0 & 5/a & 1/a \\ 0 & 5/a & 1/a \end{pmatrix}$$

$$\begin{pmatrix} a & 1 & -1 \\ 0 & 5/a & 1/a \\ 0 & 0 & 1/s \end{pmatrix} = U \quad \Rightarrow \quad J = \begin{pmatrix} 1 & 0 & 0 \\ -1/a & 1 & 0 \\ -1/a & 1 & 0 \\ -1/a & 1/s \end{pmatrix}$$
back substitution:  $Pb = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} -a \\ 17 \\ 3 \end{pmatrix} = \begin{pmatrix} 17 \\ 3 \\ -a \end{pmatrix}$ 

$$J = Pb \Rightarrow \begin{pmatrix} 1 & 0 & 0 \\ -1/a & 1 & 0 \\ -1/a & 1/s \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} -a \\ 17 \\ 3 \\ -a \end{pmatrix} \Rightarrow \begin{cases} y_1 = 17 \\ y_2 = a^2/a = 11.5 \\ y_3 = a^2/s = 4.a \end{cases}$$

$$Ux = y \implies A = \begin{pmatrix} a & 1 & -1 \\ 0 & 5/a & 1/a \\ -1/a & 1/s \\ 0 & 0 & 1/s \\ -1/a & 1/s \\ 0 & 0 & 1/s \\ -1/a & 1/s \\ -1/s & 1/s$$

4. Write a Matlab code (following the algorithm discussed in class) that takes an  $n \times n$  matrix A as input and returns P, L and U such that PA = LU. Your code should use row elimination with partial pivoting. Test your code using the matrix in text exercise 2(a) above and on a matrix generated using A=rand(6,6). In both cases, compute norm(P\*A-L\*U) to verify that your code is working correctly.

<pre>function [P,L,U] = myPLU(A) [m,n]=size(A); if m~=n     error("Matrix A is not square!") end</pre>	<pre>% Problem 4 Part (i) A=[1,1,0;2,1,-1;-1,1,-1]; [P,L,U]=myPLU(A) fprintf("norm(P*A-L*U) = %g\n", norm(P*A-L*U))</pre>							
	F =							
P=eye(n);								
L=eye(n);	0 1	0						
U=A;	0 0	1						
for k=1:n-1	1 0	0						
<pre>[pv,p] = max(abs(U(k:n, k))); p=p+k-1; if p~=k P([p,k],:)=P([k,p],:); U([p,k],:)=U([k,p],:); if k&gt;1 L([p,k],1:k-1)=L([k,p],1:k-1); end end</pre>	L = 1.0000 -0.5000 0.5000	0 1.0000 0.3333	0 0 1.0000					
<pre>for i=k+1:n     m=U(i,k)/U(k,k);     L(i,k)=m;     for j=k:n         U(i,j)=U(i,j)-U(k,j)*m;     end end end</pre>	U = 2.0000 0 0	1.0000 1.5000 0	-1.0000 -1.5000 1.0000					
	norm(P*A-L*U) = 0							

<pre>% Problem 4 Part (iI)</pre>										
A=rand(6,6);										
[P,L,U]=myPLU(A)										
<pre>fprintf("norm(P*A-L*U)</pre>	= $g\n''$ , norm(P*A-L*U))									

0.7278

-0.9116

0.7315

0.2116

P =									U =					
	0	0	1	0	0	0			0 9293	0 3517	0 7572	0 5308	0 0119	0 1656
	0	0	0	1	0	0			0.5255	0 6984	0 4685	0.5793	0 3326	0.5396
	0	1	0	0	0	0			0,000	-0.0000	-0.1683	-0.4013	0.2847	0.1906
	1	0	0	0	0	0			0.0000	0.0000	0.1009	-0.7570	0.4915	-0.0185
	0	0	0	0	0	1			0	0	0	0	0.3292	0.3368
	0	0	0	0	1	0			0	0	0	0	0	-0.4831
L =									norm(P*A-L*)	U) = 1.745.	28e-16			
	1.000	0	0		0	0	0	0						
	0.376	6	1.0000		0	0	0	0						
	0.262	1	0.5457	1.00	00	0	0	0						
	0.876.	3	0.4409	-0.27	'99	1.0000	0	0						
	0.270	2	0.6511	-0.34	56	0.6993	1.0000	0						

1.0000

0.4772

5. Consider the tridiagonal matrices

$$A = \begin{bmatrix} 2 & 3 & 0 \\ -1 & -5/2 & 2 \\ 0 & -1/4 & 3/2 \end{bmatrix}, \qquad B = \begin{bmatrix} 4 & -2 & 0 \\ -2 & 3 & 1 \\ 0 & 1 & 1 \end{bmatrix}.$$

- (a) Use direct factorization (as discussed in class) to find (by hand calculations) a lower triangular matrix L (with ones on the main diagonal) and an upper triangular matrix U such that A = LU.
- (b) Show that the symmetric matrix B is positive definite by writing  $\mathbf{x}^T B \mathbf{x}$  as a sum of squares involving the three components,  $(x_1, x_2, x_3)$ , of  $\mathbf{x}$ . Be sure to show that  $\mathbf{x}^T B \mathbf{x} = 0$  implies that  $x_1 = x_2 = x_3 = 0$ .

$$(A) \quad A = \begin{pmatrix} a & 3 & 0 \\ -1 & -\frac{5}{4}a & a \\ 0 & -\frac{1}{4} & \frac{3}{4}a \end{pmatrix} = \begin{pmatrix} u_{11} & u_{12} & u_{12} & u_{13} \\ h_{21}u_{11} & u_{22} + h_{21}u_{12} & u_{23} + h_{21}u_{13} \\ h_{31}u_{11} + h_{32}u_{22} & h_{31}u_{13} + h_{32}u_{23} + u_{33} \end{pmatrix}$$

$$u_{11} = A \implies \begin{cases} h_{21}u_{11} = -1 \implies h_{21} = -\frac{1}{4}a \\ h_{31}u_{11} = 0 \implies h_{31} = 0 \end{cases}$$

$$(u_{22} + h_{21}u_{12} = -\frac{5}{2} \implies u_{22} = -1 \\ h_{32}u_{22} + h_{21}u_{13} = -\frac{5}{2} \implies u_{23} = -1 \\ h_{32}u_{33} + h_{21}u_{13} = A \implies u_{23} = A \end{pmatrix}$$

$$u_{13} = 0 \implies \begin{cases} u_{23} + h_{21}u_{13} = A \implies u_{23} = A \\ h_{31}u_{13} + h_{32}u_{23} = \frac{3}{2} \implies u_{33} = A \end{cases}$$

$$u_{13} = 0 \implies \begin{cases} u_{11} & 0 & 0 \\ h_{21} & 1 & 0 \\ h_{31} & h_{32} & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ -\frac{1}{4}u_{12} & 0 \\ 0 & \frac{1}{4}u_{13} \end{pmatrix}$$

$$u_{13} = \begin{pmatrix} u_{11} & u_{13} & u_{13} \\ 0 & u_{23} & u_{23} \end{pmatrix} = \begin{pmatrix} 2 & 3 & 0 \\ 0 & -1 & 2 \\ 0 & 0 & 1 \end{pmatrix}$$

(b) 
$$\chi^{T}B\chi = 4\chi_{1}^{a} - 4\chi_{1}\chi_{a} + 3\chi_{a}^{b} + a\chi_{a}\chi_{3} + \chi_{3}^{b}$$
  

$$= (4\chi_{1}^{a} - 4\chi_{1}\chi_{a} + \chi_{a}^{b}) + \chi_{a}^{b} + (\chi_{a}^{b} + a\chi_{a}\chi_{3} + \chi_{3}^{b})$$

$$= (a\chi_{1} - \chi_{a})^{b} + \chi_{a}^{b} + (\chi_{a} + \chi_{3})^{b} \ge 0,$$
Now as  $\chi^{T}B\chi$  is the sum of squares, it follows that  $\chi^{T}B\chi = 0$ 

if and only if  $2X_1 - X_2 = X_2 = X_2 + X_3 = 0$ , which implies that all three components of X are zero. 6. Let

$$\mathbf{G}(\mathbf{x}) = \begin{bmatrix} \frac{1}{4}(x_1 - x_2 - 1) \\ \alpha(x_1^2 - 1) + x_2 \end{bmatrix}, \qquad \mathbf{F}(\mathbf{x}) = \begin{bmatrix} \frac{1}{2}x_1 - x_2 - 1 \\ x_1^2 - x_2^2 - 1 \end{bmatrix}.$$

- (a) Show that  $\mathbf{G}(\mathbf{x})$  has a fixed point  $\mathbf{x}^* = (-1, 2)$  for any value of the constant  $\alpha$ . Analyze the eigenvalues of the Jacobian matrix  $J = \partial \mathbf{G} / \partial \mathbf{x}$  to determine whether the fixed-point iteration  $\mathbf{x}_{k+1} = \mathbf{G}(\mathbf{x}_k)$  is locally convergent when  $(i)\alpha = -1/4$  or when (ii)  $\alpha = 1/2$ .
- (b) Let  $f_1(x_1, x_2)$  and  $f_2(x_1, x_2)$  be the two component functions of  $\mathbf{F}(\mathbf{x})$ . Plot the graphs of  $f_1 = 0$  and  $f_2 = 0$  in the  $x_1 x_2$  plane to estimate the roots  $\mathbf{x} = \mathbf{r}$  of  $\mathbf{F}$ . Write a Matlab code to determine all roots of  $\mathbf{F}$  using Newton's method. Output  $\mathbf{x}_k$ , the  $k^{\text{th}}$  iterate in Newton's method, and  $||\mathbf{x}_k \mathbf{x}_{k-1}||$  to verify quadratic convergence.

(a) 
$$G_{1}(x^{*}) = \begin{pmatrix} \frac{1}{4}(-1-a-1) \\ \alpha(1-1)+a \end{pmatrix} = \begin{pmatrix} -1 \\ a \end{pmatrix} = x^{*}, \text{ thus } x^{*} \text{ is a fixed point of } G(x) \\ \text{regardless of the value of constant } \alpha \\ J = \begin{pmatrix} \frac{36_{11}}{3\pi}, & \frac{36_{11}}{3\pi} \\ \frac{36_{22}}{3\pi}, & \frac{36_{22}}{3\pi} \end{pmatrix} = \begin{pmatrix} \frac{1}{4} & -\frac{1}{4} \\ a\alpha x_{1} & 1 \end{pmatrix} \Longrightarrow J_{c-1,a} = \begin{pmatrix} \frac{1}{4} & -\frac{1}{4} \\ -a\alpha & 1 \end{pmatrix}$$
  
At  $\alpha = -\frac{1}{4}, J_{1} = \begin{pmatrix} \frac{1}{4} - \lambda & -\frac{1}{4} \\ \frac{1}{4} & 1 \end{pmatrix}$   
 $det(J_{1} - \lambda I) = \begin{vmatrix} \frac{1}{4} - \lambda & -\frac{1}{4} \\ \frac{1}{4} & 1 - \lambda \end{vmatrix} = \lambda^{a} - \frac{5}{4}\lambda + \frac{1}{4} + \frac{1}{8} = \lambda^{a} - \frac{5}{4}\lambda + \frac{3}{8}$   
 $set \lambda^{a} - \frac{5}{4}\lambda + \frac{3}{8} = 0 \implies (\lambda - \frac{1}{a})(\lambda - \frac{3}{4}) = 0$   
 $\lambda_{1} = \frac{1}{a}, \lambda_{2} = \frac{3}{4}$   
 $max\{|\lambda_{2}|\} < 1$   
Therefore, when  $\alpha = -\frac{1}{4}$ , the fixed-point iteration is beally convergent.

At 
$$\alpha = \frac{1}{2}$$
,  $J_{\alpha} = \begin{pmatrix} \frac{1}{4} & -\frac{1}{4} \\ -1 & 1 \end{pmatrix}$   

$$det (J_{\alpha} - \lambda I) = \begin{vmatrix} \frac{1}{4} - \lambda & -\frac{1}{4} \\ \frac{1}{4} - \lambda \end{vmatrix} = \lambda^{\alpha} - \frac{5}{4}\lambda + \frac{1}{4} - \frac{1}{4} = \lambda^{\alpha} - \frac{5}{4}\lambda$$

$$set \lambda^{\alpha} - \frac{5}{4}\lambda = 0 \implies \lambda (\lambda - \frac{5}{4}) = 0$$

$$\lambda_{1} = 0, \quad \lambda_{\alpha} = \frac{5}{4}$$

$$max \{ |\lambda_{i}| \} > 1$$

Therefore, when  $\alpha = \frac{1}{\alpha}$ , the fixed-point iteration is NOT boally convergent.



```
function x=myNewtonNL(f,fp,x0)
  tol=1e-12;
  nMax=10;
  <prexpre=[0;0];</pre>
  x=x0;
  n=0;
  while n<nMax && abs(norm(x-xpre))>tol
      xpre=x:
      s=fp(x) - f(x);
      x=s+x;
      n=n+1;
      fprintf("iteration %d x=[%3.5f; %3.5f;] err=%8e\n",n,x(1,:),x(2,:),norm(x-
  xpre))
  end
  end
f=@(x)[1/2*x(1)-x(2)-1; x(1)^2-x(2)^2-1];
fp=@(x)[1/2 -1; 2*x(1) -2*x(2)];
x0=[1; -0.5];
myNewtonNL(f, fp, x0)
x0=[-2.5; -2];
```

```
iteration 1 x=[1.10000; -0.45000;] err=1.118034e-01
iteration 2 x=[1.09717; -0.45142;] err=3.164247e-03
iteration 3 x=[1.09717; -0.45142;] err=2.538619e-06
iteration 4 x=[1.09717; -0.45142;] err=1.633781e-12
iteration 5 x=[1.09717; -0.45142;] err=2.482534e-16
```

```
ans =
```

```
1.0972
-0.4514
```

myNewtonNL(f, fp, x0)

```
iteration 1 x=[-2.41667; -2.20833;] err=2.243819e-01
iteration 2 x=[-2.43056; -2.21528;] err=1.552825e-02
iteration 3 x=[-2.43050; -2.21525;] err=6.113484e-05
iteration 4 x=[-2.43050; -2.21525;] err=9.476218e-10
iteration 5 x=[-2.43050; -2.21525;] err=4.440892e-16
```

ans =

-2.4305 -2.2153