

Assignment 3, due before class, Thursday June 15, 2023.

Haowen He heh4@rpi.edu

1. Let

$$A = \begin{bmatrix} 1 & -2 & -1 \\ \alpha & 3 & 1 \\ -1 & \alpha & 1 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} \beta \\ -4 \\ 2 \end{bmatrix}$$

and let \mathbf{x} be the solution of $A\mathbf{x} = \mathbf{b}$, if it exists. Determine conditions on the constants α and β such that (a) a solution or solutions exist and (b) a unique solution exists.

$$\begin{aligned} \text{(a)} \quad \det(A) &= 1 \cdot (3 - \alpha) - (-2)(\alpha + 1) - 1 \cdot (\alpha^2 + 3) \\ &= 3 - \alpha + 2\alpha + 2 - \alpha^2 - 3 \\ &= -\alpha^2 + \alpha + 2 \end{aligned}$$

$$\text{when } \det(A) \neq 0, \quad -\alpha^2 + \alpha + 2 \neq 0$$

$$(\alpha - 2)(\alpha + 1) \neq 0$$

$$\alpha \neq -1, 2$$

matrix A is non-singular, and thus, a solution exists.

$$\text{when } \alpha = -1, \quad \left(\begin{array}{ccc|c} 1 & -2 & -1 & \beta \\ -1 & 3 & 1 & -4 \\ -1 & -1 & 1 & 2 \end{array} \right) \begin{array}{l} R_2 \rightarrow R_1 + R_2 \\ R_3 \rightarrow R_1 + R_3 \end{array}$$

$$\left(\begin{array}{ccc|c} 1 & -2 & -1 & \beta \\ 0 & 1 & 0 & \beta - 4 \\ 0 & -3 & 0 & \beta + 2 \end{array} \right) \xrightarrow{R_3 \rightarrow 3R_2 + R_3} \left(\begin{array}{ccc|c} 1 & -2 & -1 & \beta \\ 0 & 1 & 0 & \beta - 4 \\ 0 & 0 & 0 & 4\beta - 10 \end{array} \right)$$

in order for solutions to exist, $4\beta - 10 = 0 \Rightarrow \beta = \frac{5}{2}$.

when $\alpha = 2$, $\left(\begin{array}{ccc|c} 1 & -2 & -1 & \beta \\ 2 & 3 & 1 & -4 \\ -1 & 2 & 1 & 2 \end{array} \right) \xrightarrow{\substack{R_2 \rightarrow R_2 - 2R_1 \\ R_3 \rightarrow R_1 + R_3}}$

$\left(\begin{array}{ccc|c} 1 & -2 & -1 & \beta \\ 0 & 7 & 3 & -4 - \beta \\ 0 & 0 & 0 & \beta + 2 \end{array} \right)$ in order for solutions to exist,

$$\beta + 2 = 0 \Rightarrow \beta = -2.$$

Therefore, when $\alpha \neq -1, 2$ or $\alpha = -1, \beta = 5/2$, or $\alpha = 2, \beta = -2$,

a solution or solutions exist.

(b) When $\alpha \neq -1, 2$, determinant of A is non-zero. It

follows that matrix A is non-singular, which implies that

A is invertible, and thus $A^{-1}b$ is a unique solution of

$Ax = b$, regardless of the value of β we choose.

2. (a) Consider the two augmented matrices of the form $[A|\mathbf{b}]$ in text exercise 4 on page 81. For each matrix, use row operations to reduce it to the upper triangular form $[U|\mathbf{c}]$ and then find the solution of $U\mathbf{x} = \mathbf{c}$ using backwards substitution.

(b) Text exercise 6 and 7 on page 82.

$$(a) \begin{pmatrix} 3 & -4 & -2 & | & 3 \\ 6 & -6 & 1 & | & 2 \\ -3 & 8 & 2 & | & -1 \end{pmatrix} \xrightarrow{\substack{R_2 \rightarrow R_2 - 2R_1 \\ R_3 \rightarrow R_3 + R_1}} \begin{pmatrix} 3 & -4 & -2 & | & 3 \\ 0 & 2 & 5 & | & -4 \\ 0 & 4 & 0 & | & 2 \end{pmatrix}$$

$$\xrightarrow{R_3 \rightarrow R_3 - 2R_2} \begin{pmatrix} 3 & -4 & -2 & | & 3 \\ 0 & 2 & 5 & | & -4 \\ 0 & 0 & -10 & | & 10 \end{pmatrix} = [U|\mathbf{c}]$$

$$\begin{cases} -10x_3 = 10 \\ 2x_2 + 5x_3 = -4 \\ 3x_1 - 4x_2 - 2x_3 = 3 \end{cases} \Rightarrow \begin{cases} x_3 = -1 \\ 2x_2 = -4 + 5 = 1 \Rightarrow x_2 = \frac{1}{2} \\ 3x_1 = 3 + 2 - 2 = 3 \Rightarrow x_1 = 1 \end{cases}$$

$$\text{Solution } \mathbf{x} = \begin{pmatrix} 1 \\ \frac{1}{2} \\ -1 \end{pmatrix}$$

$$\begin{pmatrix} 2 & 1 & -1 & | & 2 \\ 6 & 2 & -2 & | & 8 \\ 4 & 6 & -3 & | & 5 \end{pmatrix} \xrightarrow{\substack{R_2 \rightarrow R_2 - 3R_1 \\ R_3 \rightarrow R_3 - 2R_1}} \begin{pmatrix} 2 & 1 & -1 & | & 2 \\ 0 & -1 & 1 & | & 2 \\ 0 & 4 & -1 & | & 1 \end{pmatrix}$$

$$\xrightarrow{R_3 \rightarrow R_3 + 4R_2} \begin{pmatrix} 2 & 1 & -1 & | & 2 \\ 0 & -1 & 1 & | & 2 \\ 0 & 0 & 3 & | & 9 \end{pmatrix}$$

$$\begin{array}{l}
 3x_3 = 9 \\
 -x_2 + x_3 = 2 \\
 2x_1 + x_2 - x_3 = 2
 \end{array}
 \left. \vphantom{\begin{array}{l} 3x_3 = 9 \\ -x_2 + x_3 = 2 \\ 2x_1 + x_2 - x_3 = 2 \end{array}} \right\}
 \begin{array}{l}
 x_3 = 3 \\
 -x_2 = 2 - 3 = -1 \Rightarrow x_2 = 1 \\
 2x_1 = 2 - 1 + 3 = 4 \Rightarrow x_1 = 2
 \end{array}$$

Solution $x = \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix}$

(b) Given that the computer takes 0.005 seconds to perform back-substitution which has complexity of $O(n^2)$.

Now as a full Gaussian elimination takes approximately

$\frac{2}{3}n^3$ operations, with $n = 5000$, it follows that

$$\begin{aligned}
 & n^2 \cdot \frac{2}{3}n \\
 &= 0.005 \cdot \frac{2 \cdot 5000}{3} \\
 &\approx \boxed{17 \text{ s}} //
 \end{aligned}$$

Now given the computer takes 0.002 seconds to perform back-substitution on a 4000 by 4000 matrix, it follows that it can perform

$$\frac{4000^2}{0.002} = 8 \times 10^9 \text{ operations/second}$$

Solving a general system of 9000 equations with 9000 unknowns will take approximately $9000^2 + \frac{2}{3}9000^3 = 4.86081 \times 10^{11}$ operations, and the computer

will need approximately $\frac{4.86081 \times 10^{11}}{8 \times 10^9} \approx \boxed{61 \text{ s}}$ to compute.

3. Let \hat{A} be an $n \times (n + 2)$ matrix and consider the following steps in a Matlab code:

```

for kb=1:2
  x(n,kb)=Ahat(n,n+kb)/Ahat(n,n);
  for i=n-1:-1:1
    sum=Ahat(i,n+kb);
    for j=i+1:n
      sum=sum-Ahat(i,j)*x(j,kb);
    end
    x(i,kb)=sum/Ahat(i,i);
  end
end
end

```

Determine the number of flops used to compute the elements of \mathbf{x} for a given positive integer n . (Find an expression for the number of flops exactly, without approximation for large n .)

$$\begin{aligned}
 \text{Divisions } \mathcal{F}_d &= \sum_{kb=1}^2 1 + \sum_{kb=1}^2 \sum_{i=1}^{n-1} 1 \\
 &= 2 + 2(n-1) \\
 &= 2n
 \end{aligned}$$

$$\begin{aligned}
 \text{Multiplications } \mathcal{F}_m &= \sum_{kb=1}^2 1 \sum_{j=i+1}^n 1 = \sum_{kb=1}^2 1 \sum_{i=1}^{n-1} (n - (i+1) + 1) \\
 &= 2 \sum_{i=1}^{n-1} (n-i) = 2 \left(\sum_{i=1}^{n-1} n - \sum_{i=1}^{n-1} i \right) \\
 &= 2 \left(n \sum_{i=1}^{n-1} 1 - \sum_{i=1}^{n-1} i \right) \\
 &= 2n(n-1) - 2 \cdot \frac{n(n-1)}{2} \\
 &= 2n^2 - 2n - n^2 + n \\
 &= n^2 - n
 \end{aligned}$$

Additions $\mathcal{F}_a = n^2 - n$ same as multiplication
 one floating-point subtraction from each multiplication

$$\text{Total} = 2n + n^2 - n + n^2 - n = \boxed{2n^2 \text{ flops}} //$$

4. (a) Write a `Matlab` code to compute the LU -decomposition of a given $n \times n$ matrix A following the algorithm discussed in class. Your code need not perform row interchanges (pivoting), but should check for very small pivot elements and provide a warning if one is encountered.

(b) Use your code to compute the L and U factors for the following matrices:

(i) $A = \begin{bmatrix} 6 & 3 & 2 \\ -1 & 4 & 2 \\ 1 & 3 & -5 \end{bmatrix}$; (ii) $A = \text{hilb}(5)$;

Print out L and U and compute $\text{norm}(A-L*U)$ for each case. The latter is `Matlab`'s calculation of the distance (i.e. norm) between A and the product LU . What are the expected values for this norm?

```
function [L,U] = myLU(A)

[m,n]=size(A);
if m~=n
    error("Matrix is not square!")
end
L=eye(n);
U=A;

for k=1:n-1
    if abs(U(k,k))<10e-16
        printf("Warning: value less than 1-e-16\n");
    end

    for i=k+1:n
        L(i,k)=U(i,k)/U(k,k);
        for j=k:n
            U(i,j)=U(i,j)-L(i,k)*U(k,j);
        end
    end
end

% HW 3 Problem 4 part (i)
[L,U] = myLU([6 3 2; -1 4 2; 1 3 -5])
norm([6 3 2; -1 4 2; 1 3 -5]- L*U)
% HW 3 Problem 4 part (ii)
[L,U] = myLU(hilb(5))
norm(hilb(5)- L*U)
```

Part i

Part ii

L =

1.0000	0	0
-0.1667	1.0000	0
0.1667	0.5556	1.0000

L =

1.0000	0	0	0	0
0.5000	1.0000	0	0	0
0.3333	1.0000	1.0000	0	0
0.2500	0.9000	1.5000	1.0000	0
0.2000	0.8000	1.7143	2.0000	1.0000

U =

6.0000	3.0000	2.0000
0	4.5000	2.3333
0	0	-6.6296

U =

1.0000	0.5000	0.3333	0.2500	0.2000
0	0.0833	0.0833	0.0750	0.0667
0	-0.0000	0.0056	0.0083	0.0095
0	0	0	0.0004	0.0007
0	0	0	0	0.0000

ans =

0

ans =

4.4909e-17

5. (a) An $n \times n$ elimination matrix M has the form

$$M = \begin{bmatrix} 1 & & & & \\ & \ddots & & & \\ & & 1 & & 0 \\ & & -m_{k+1,k} & & \\ 0 & & \vdots & 0 & \ddots \\ & & -m_{n,k} & & 1 \end{bmatrix} \quad \text{for some integer } k \in [1, n-1]$$

Find 4×4 elimination matrices M_1 and M_2 satisfying

$$M_1 \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \quad M_2 \begin{bmatrix} 2 \\ -1 \\ 4 \\ -3 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \\ 0 \\ 0 \end{bmatrix}$$

(b) An $n \times n$ permutation matrix P is a row or column permutation of the $n \times n$ identity matrix. Thus, P has exactly one 1 in every column and row. The following are examples of 3×3 permutation matrices

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}, \quad \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}, \quad \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Find 4×4 permutation matrices P_1 and P_2 satisfying

$$P_1 \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \\ 3 \\ 2 \end{bmatrix}, \quad P_2 \begin{bmatrix} 2 \\ -1 \\ 4 \\ -3 \end{bmatrix} = \begin{bmatrix} 4 \\ -1 \\ -3 \\ 2 \end{bmatrix}$$

$$\begin{array}{ccc} (a) & 2 - 2 \cdot 1 = 3 - 3 \cdot 1 = 4 - 4 \cdot 1 = 0 \\ & \Downarrow & \Downarrow & \Downarrow \\ & m_{2,1} = 2 & m_{3,1} = 3 & m_{4,1} = 4 \end{array}$$

$$M_1 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ -2 & 1 & 0 & 0 \\ -3 & 0 & 1 & 0 \\ -4 & 0 & 0 & 1 \end{pmatrix}$$

$$4 + 4 \cdot (-1) = -3 - 3 \cdot (-1) = 0$$



$$m_{3,2} = -4$$



$$m_{4,2} = 3$$

$$M_2 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 4 & 1 & 0 \\ 0 & -3 & 0 & 1 \end{pmatrix}$$

By definition given above, elimination matrix M has the form of $\begin{pmatrix} 1 & & & 0 \\ & 1 & & \\ 0 & & 1 & \\ & & & 1 \end{pmatrix}$, where the bottom entries should be in the same column.

$$(b) \quad P_1 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} \quad P_2 = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

For permutation matrix P , the product PA is a new matrix whose rows consists of the rows of A rearranged in the new order.